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This well-respected work discusses the use of digital computers in the real-time control of dynamic systems. The emphasis is on the design of digital controls that achieve good dynamic response and small errors while using signals that are sampled in time and quantized in amplitude. MATLAB statements and problems are thoroughly and carefully integrated throughout the book to offer readers a complete design picture.

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Among the advantages of digital logic for control are the increased flexibility of the control programs and the decision-making or logic capability of digital systems, which can be combined with the dynamic control function to meet other system requirements. The digital controls studied in this book are for closed-loop (feedback)

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Multiple Choice Questions and Answers on Control Systems Multiple Choice Questions and Answers By Sasmita January 9, 2020 1) Which terminology deals with the excitation or stimulus applied to the system from an external source for the generation of an output?

Introduction; Review of continuous control; Introductory digital control; Discrete systems analysis; Sampled-data systems; Discrete equivalents; Design using transform techniques; Design using state-space methods; Multivariable and optimal control; Quantization effects; Sample rate selection; System identification; Nonlinear control; Design of a disk drive servo: a case study; Appendix A: Examples; Appendix B: Tables; Appendix C; A few results from matrix analysis; Appendix D: Summary of facts from the theory of probability and stochastic processes; Appendix E: Matlab functions; Appendix F; Differences between Matlab v5 and v4; References; Index.

This work discusses the use of digital computers in the real-time control of dynamic systems using both classical and modern control methods. Two new chapters offer a review of feedback control systems and an overview of digital control systems. MATLAB statements and problems have been more thoroughly and carefully integrated throughout the text to offer students a more complete design picture.

Discusses the use of digital computers in the real-time control of dynamic systems.

Textbook about the use of digital computers in the real-time control of dynamic systems such as servomechanisms, chemical processes, and vehicles that move over water, land, air, or space. Requires some understanding of the Laplace transform and assumes a first course in linear feedback controls. An

This is a senior level or 1st year graduate level text that covers how to design and implement control systems in digital computers. The Ellis-Kagle Press printing is the same as the original AW printing of this 1998 3rd edition, but has all known errors corrected.

This well-respected work discusses the use of digital computers in the real-time control of dynamic systems. The emphasis is on the design of digital controls that achieve good dynamic response and small errors while using signals that are sampled in time and quantized in amplitude. Both classical and modern control methods are described and applied to illustrative examples. The strengths and limitations of each method are explored to help the reader develop satisfactory designs with the least effort. Two new chapters have been added to the third edition offering a review of feedback control systems and an overview of digital control systems. MATLAB statements and problems have been more thoroughly and carefully integrated throughout the book to offer readers a more complete design picture. The new edition contains up-to-date material on state-space design and twice as many end-of-chapter problems. Copyright © Libri GmbH. All rights reserved.

This is the eBook of the printed book and may not include any media, website access codes, or print supplements that may come packaged with the bound book. For senior-level or first-year graduate-level courses in control analysis and design, and related courses within engineering, science, and management. Feedback Control of Dynamic Systems, Sixth Edition is perfect for practicing control engineers who wish to maintain their skills. This revision of a top-selling textbook on feedback control with the associated web site, FPE6e.com, provides greater instructor flexibility and student readability. Chapter 4 on A First Analysis of Feedback has been substantially rewritten to present the material in a more logical and effective manner. A new case study on biological control introduces an important new area to the students, and each chapter now includes a historical perspective to illustrate the origins of the field. As in earlier editions, the book has been updated so that solutions are based on the latest versions of MATLAB and SIMULINK. Finally, some of the more exotic topics have been moved to the web site.

This tutorial provides a variety of simulation algorithms for the design and control of dynamic systems. It explains the accuracy and stability of automatic control theory, emphasizing those systems described by stiff non-linear differential equations.

An integrated presentation of both classical and modern methods of systems modeling, response and control. Includes coverage of digital control systems. Details sample data systems and digital control. Provides numerical methods for the solution of differential equations. Gives in-depth information on the modeling of physical systems and central hardware.

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